



CIGRE SC B5. Workshop

EFFECT OF GENERATOR CONTROLS ON PROTECTIVE RELAY SETTINGS

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Oct 22nd, 2019

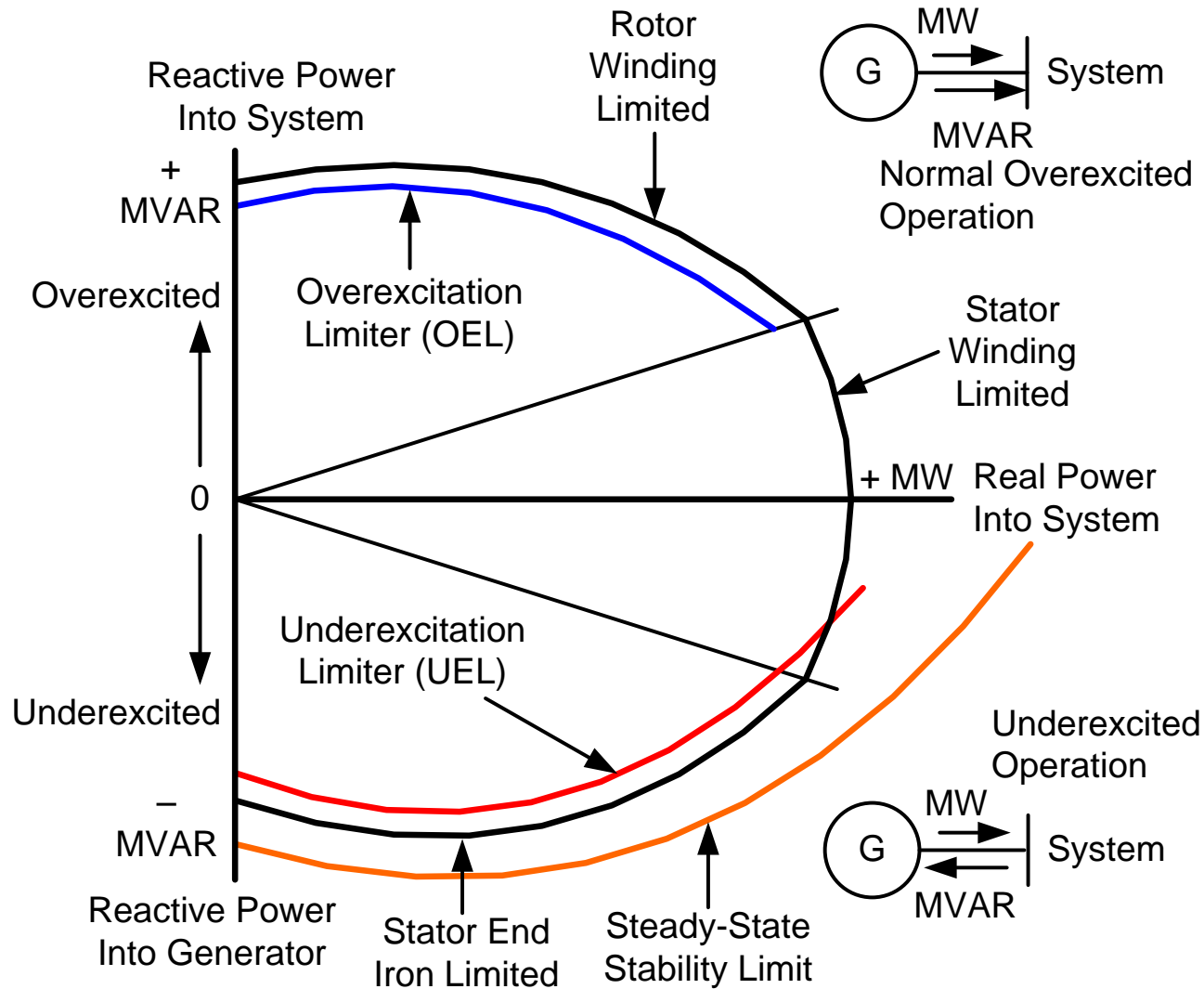
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Content

- Fundamentals
- Protection schemes and setting criteria suggested by IEEE Std C37.102-2006
- NERC Regulations 019, 024, 025 and 026
- Case Study

Typical Generator Capability Curve P-Q Diagram



Typical Settings of Generator Relays

Table 1 - Recommended Settings

IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
21	Distance	4.6.1.1 & A.2.3	Zone-1 = smaller of the two following criteria: 1. 120% of unit transformer 2. 80% of Zone 1 reach setting of the line relay on the shortest line (neglecting in-feed); time = 0.5 s
			Zone-2 = the smaller of the three following criteria: A. 120% of longest line (with in-feed). If the unit is connected to a breaker and a half bus, this would be the length of the adjacent line. B. 50% to 66.7% of load impedance (150% to 200% of the generator capability curve) at the RPFA C. 80% to 90% of load impedance (111% to 125% of the generator capability curve) at the maximum torque angle; time > 60 cycles
			Note: Maximum load impedance at rated power factor does not encroach into the reach. A value of 150% to 200% is recommended to avoid tripping during normal load. Zone2<2Zmax_load @ RPF
24	Overexcitation	4.5.4.2 & A.2.10	Single relay: PU = 110% p.u. time = 6 s
			Two stages relay: alarm pu = 110%; 45< t < 60 s trip pu = 118% - 120%, 2< t < 6s
25	Sync-check	5.7	Breaker closing angle: within ± 10 elect. Degrees
			Voltage matching: 0 to +5%
			Frequency difference < 0.067 Hz
27	Undervoltage	4.5.7 & A.2.13	<i>Relays with inverse time charac and instantaneous</i> Pickup: 90%Vn; t= 9.0 s at 90% of pickup setting Inst : 70% Vn
			<i>Relays with definite time charac and 2 stages</i> FS - Alarm pickup: 90%Vn; 10< t < 15 s SS - Trip pickup: 80% Vn; time: 2s

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
32	Reverse Power	4.5.5.3 & A.2.9	Pickup setting should be below the following motoring limits: Gas : 50% rated power; time < 60 s Diesel : 25% rated power; time < 60 s Hydro turbines : 0.2% - 2% rated power; time < 60 s Steam turbines : 0.5% - 3% rated power; time < 30 s
40	Loss-of-field Approach # 1	4.5.1.3 & A.2.1	UNIT 1 Offset: $X'_d/2$; Diameter: 1.0 pu; time: 0.1 s UNIT 2 Offset: $X'_d/2$; Diameter: X_d ; time: 0.5 to 0.6 s
	Loss-of-field Approach # 2		UNIT 1 Offset: $X'_d/2$; Diameter: $1.1 X_d - X'_d/2$ or $1.25X_d - X'_d/2$; Time: 0.25 s UNIT 2 Offset: $X_{TG} + X_{min SG1}$; Diameter: $1.1 X_d + X_{TG} + X_{min SG1}$ or $1.25 X_d + X_{TG} + X_{min SG1}$ Time: $1.0 s < t < 60 s$. Angle of directional element = -13°

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
46	Negative Sequence Overcurrent	4.5.2 & A.2.8	<p>Pickup setting should be below the permissible I_2 percent expressed in percent of rated current, which are indicated below:</p> <p><i>Salient pole: 10%</i></p> <p> With connected amortisseur windings : 10%</p> <p> With non-connected amortisseur windings : 5%</p> <p><i>Cylindrical rotor</i> Indirectly cooled : 10%</p> <p>Directly cooled - Up to 350 : 8%</p> <p> - 351 MVA TO 1250 MVA : 8% (MVA-350)/300</p> <p> - 1251MVA TO 1600 MVA : 5%</p> <p><u>Permissible K ($I_2^2 t$)</u></p> <p>Salient pole generator : 40</p> <p>Synchronous condenser : 30</p> <p>Cylindrical rotor indirectly cooled : 30</p> <p>Cylindrical rotor directly cooled (0 MVA to 800 MVA) : 10</p> <p>Directly cooled (801 MVA -1600 MVA) : See Figure 4-39</p>
50/87	Differential via flux summation CTs or split-phase protection	4.3.2.5.1	The pickup of the instantaneous unit should be set above the CT error currents that may occur during external faults. The resulting settings offers little turn fault protection.
50/27	Inadvertent Energization Overcurrent with 27, 81 Supervision	5.4.2.4 & A.2.4	50: pickup \leq 50% of the worst-case current value and should be $>$ 125% generator rated current. 27: 50% V_n , time: 1.5 s

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
50 BF	Generator Breaker Failure Protection	4.7 & A.2.11	Current detector: pickup should be more sensitive than the lowest current present during fault involving currents. Timer > Generator breaker interrupt time + Curr det. dropout time + safety margin
51N	Stator Ground Over-current (Low, Med Z Gnd, Phase CT Residual)	4.3.3.2	The grounding resistor is selected to limit the generator's contribution to a single phase-to-ground fault at its terminals to a range of current between 200 A and 150% rated full load current
50/51N	Stator Ground Over-current (Low, Med Z Gnd, Neutral CT or Flux Summation CT)		
51GN, 51N	Stator Ground Over-current (High Z Gnd)	4.3.3.1.1	Typically, the overvoltage relay has minimum pickup setting of approximately 5 V. With this setting and with typical distribution transformer ratios, this scheme is capable of detecting faults to within 2% to 5% of the stator neutral.
50/51	Time overcurrent protection (against overloads)	4.1.1.2	51 pickup: 75-100% FLC, time: 7 s at 218% FLC. FLC means full load current. 50 pickup: 115% FLC, time: instantaneous unit is set to pick up at 115% of full-load current and is used to torque control the time-overcurrent unit. The instantaneous unit dropout should be 95% of higher of pickup setting.

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
51VC	Voltage Controlled Overcurrent	4.6.1.2 & A.2.6	Overcurrent pickup: 50% FLC Control voltage: 75%Vn. Inverse time curve and dial settings should be set to coordinate with system line relays for close-in faults on the transmission lines at the plant.
51VR	Voltage Restrained Overcurrent	4.6.1.2 & A.2.6	Overcurrent pickup: 150% FLC at rated voltage Inverse time curve and dial settings should be set to coordinate with system line relays for close-in faults on the transmission lines at the plant.
59	Overvoltage	4.5.6. & A.2.12	<i>Relays with inverse time charac and instantaneous</i> Pickup: 110%Vn; t= 2.5 s at 140% of pickup setting Inst : 130 - 150% Vn <i>Relays with definite time charac and 2 stages</i> Alarm pickup : 110%Vn; 10< t < 15 s Trip pickup : 150% Vn; time: 2 cycles<t<5 cycles
59N, 27-TH, 59P	100% Stator Gound protection (for high impedance grounding generators)	4.3.3.1.1 & A.2.7	59G element: Pickup = 5 V; t = 5 s Time setting must be selected to provide coordination with other system protective devices. 27TH element: Pickup = 50% neutral third harmonic voltage, time = 5 s
64F	Generator Rotor Field protection (rotor ground faults)	4.4.1	<u>Field ground detection using DC a source: 1< t <3 s</u> <u>Field ground detection for Brushless Machines with telemetry infrared LED communications: time up to 10 s</u> <u>Field ground detection using low frequency square wave voltage injection:</u> ALARM = 20 kOhm TRIP = 5 kOhm

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
67IE	Directional O/C for Inadvertent Energization		
78	Out of Step	4.5.3 & A.2.2	<p>Mho Diameter : $2X'_d + 1.5 X_{TG}$ Blinder distance (d) = $((X'_d + X_{TG} + X_{maxSG1})/2) \times \tan(90-(d/2))$; d: angular separation between generator and the system which the relay determines instability. <u>If there is not stability study available</u> $d = 120^\circ$ t = as per transient stability study Typically $40 < t < 100$ ms</p>
81	Over/under frequency (60 Hz systems)	4.5.8 & A.2.14	<p>Typical Setting 81U ALARM: 59.5 Hz Time: 10 s. The underfrequency load shedding setting in the systems is given as 59.3 Hz with a delay of 14 cycles. 81U TRIP: The generator 81U relay should be set below the pick-up of underfrequency load shedding relay set-point and above the off frequency operating limits of steam turbine. 81O ALARM: Pick-up: 60.6 Hz, Time Delay 5 sec.</p>

Typical Settings of Generator Relays

Table 1 - Recommended Settings			
IEEE No.	FUNCTION	Per IEEE C37.102	
		SECTION	DESCRIPTION
87G	Generator Phase Differential	4.3.3.2 & A.2.5	Pickup : 0.3 A Slope : 10% time: instantaneous
87GN	Generator Ground Differential	4.3.2	
87UD	Unit Differential	4.3.2.6	

NERC Standards

NERC Standards have to be considered and in particular the following:

- Standard PRC-019-2 — Coordination of Generating Unit or Plant Capabilities, Voltage Regulating Controls, and Protection
- Standard PRC-024-1 — Generator Frequency and Voltage Protective Relay Settings
- Standard PRC-025-1— Generator Relay Loadability
- Standard PRC-026-1 – Relay Performance During Stable Power Swings

Standard PRC-019-2 — Coordination of Generating Unit or Plant Capabilities, Voltage Regulating Controls, and Protection

A. Introduction

- 1. Title:** Coordination of Generating Unit or Plant Capabilities, Voltage Regulating Controls, and Protection
- 2. Number:** PRC-019-2
- 3. Purpose:** To verify coordination of generating unit Facility or synchronous condenser voltage regulating controls, limit functions, equipment capabilities and Protection System settings.

NERC PRC-019-2

- The use of a transient stability study is required to demonstrate this coordination.
- NERC PRC-019-2 requires the generator owner to verify the following coordination items:
 - The in-service limiters (field over and under-excitation limiters) are set to operate before the Protection System (Function 40) to avoid disconnecting the generator unnecessarily.
 - The generator protection system devices (Functions 40 and 78) are set to operate to isolate equipment in order to limit the extent of damage when operating conditions exceed equipment capabilities or stability limits (steady and transient).

NERC PRC-019-2

- Per NERC PRC-019-2, the diagram should include the equipment capabilities and the operating region for the limiters and protection functions. The following are typical:
 - Generator Capability Curve (under and over-excited operation)
 - Over Excitation Limiter (OEL) and Over Excitation Trip (OEP)
 - Under Excitation Limiter (UEL) and Minimum Excitation Trip (MEP)
 - System Steady-State Stability Limit (SSSL)
 - Zone 1 and 2 of Loss of Field Protection (40)
- The Steady State Stability Limit (SSSL) is the limit to synchronous stability in the under-excited region with fixed field current. It can be calculated using generator reactance parameters and system impedances.

NERC PRC-024-1

Standard PRC-024-1 — Generator Frequency and Voltage Protective Relay Settings

A. Introduction

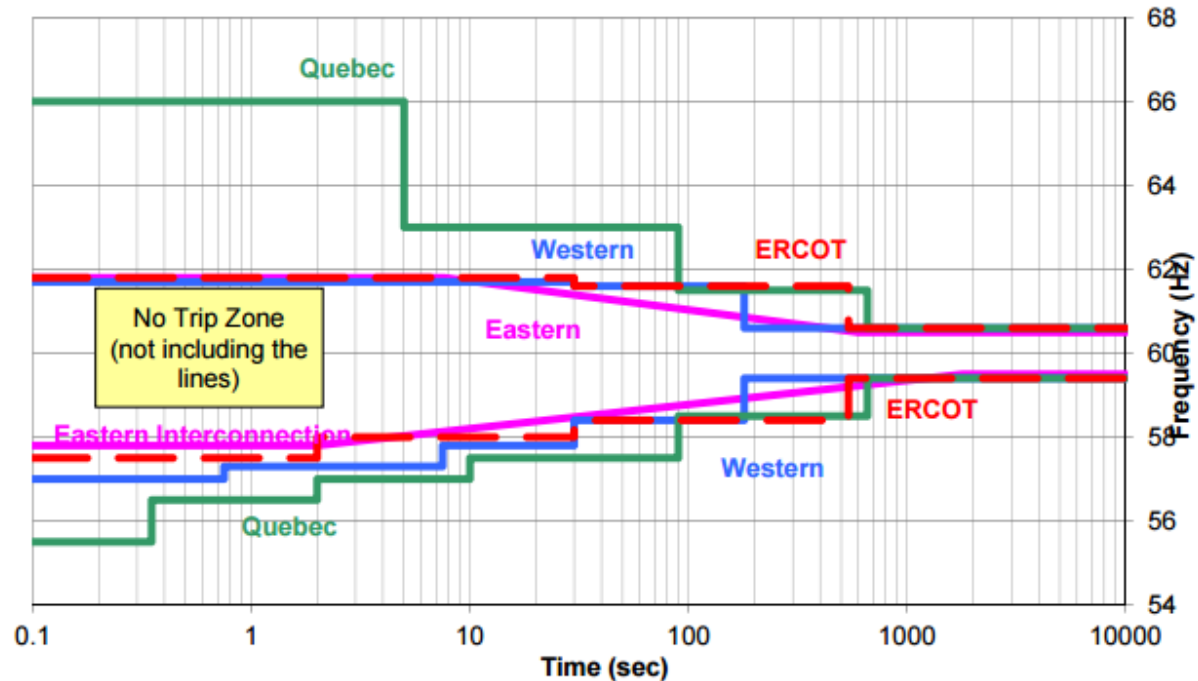
1. **Title:** Generator Frequency and Voltage Protective Relay Settings
2. **Number:** PRC-024-1
3. **Purpose:** Ensure Generator Owners set their generator protective relays such that generating units remain connected during defined frequency and voltage excursions.
4. **Applicability:**
 - 4.1. Generator Owner

NERC PRC-024-1

Standard PRC-024-1 — Generator Frequency and Voltage Protective Relay Settings

PRC-024 — Attachment 1

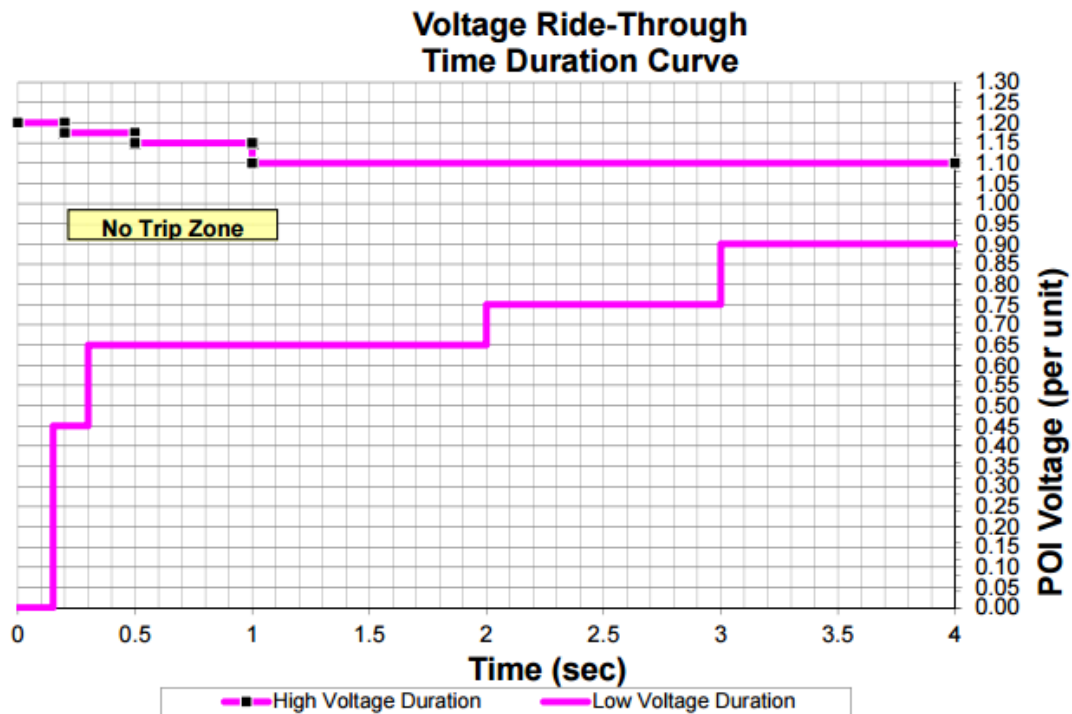
OFF NOMINAL FREQUENCY CAPABILITY CURVE



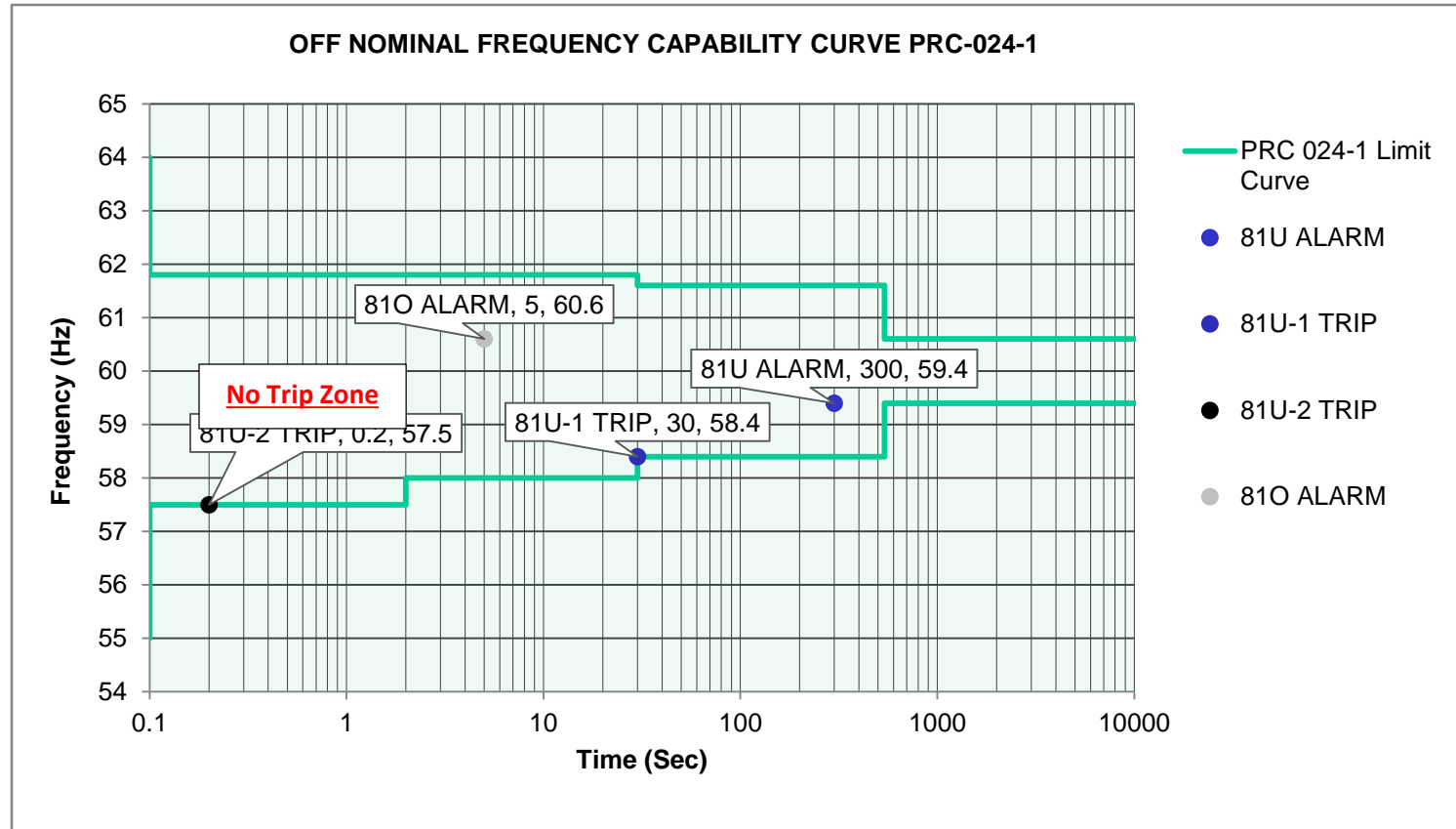
NERC PRC-024-1

Standard PRC-024-1 — Generator Frequency and Voltage Protective Relay Settings

PRC-024— Attachment 2

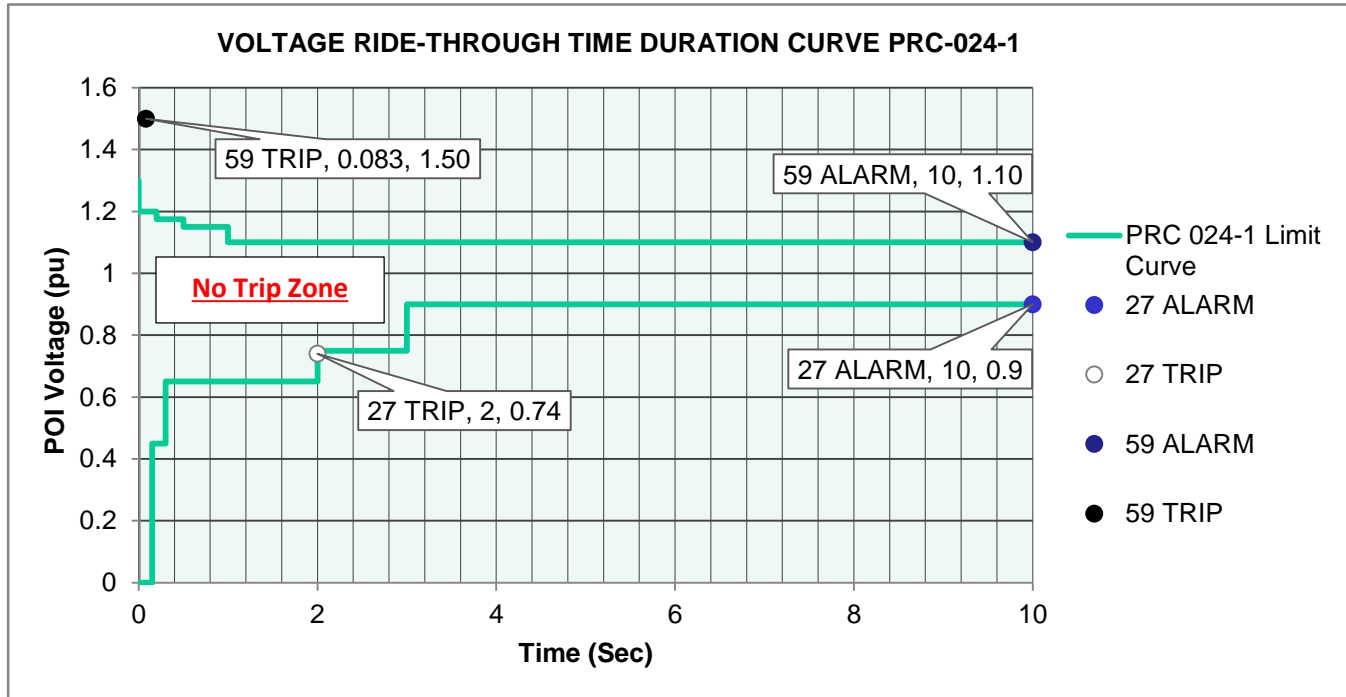


NERC PRC-024-1 – Case Study



**Graphical Verification of Coordination per Standard PRC-024-1
– Frequency (ERCOT Interconnection)**

NERC PRC-024-1 – Case Study



Graphical Verification of Coordination per Standard PRC-024-1 - Voltage

PRC-025-1— Generator Relay Loadability

A. Introduction

1. **Title:** **Generator Relay Loadability**
2. **Number:** **PRC-025-1**

Purpose: To set load-responsive protective relays associated with generation Facilities at a level to prevent unnecessary tripping of generators during a system disturbance for conditions that do not pose a risk of damage to the associated equipment.

Example Calculations: Option 1a

$$Z_{sec} = 0.321 \angle 58.7^\circ \Omega \times \frac{\frac{25000}{5}}{\frac{200}{1}}$$

$$Z_{sec} = 0.321 \angle 58.7^\circ \Omega \times 25$$

$$Z_{sec} = 8.035 \angle 58.7^\circ \Omega$$

To satisfy the 115% margin in Option 1a:

$$\text{Eq. (7)} \quad Z_{sec \text{ limit}} = \frac{Z_{sec}}{115\%}$$

$$Z_{sec \text{ limit}} = \frac{8.035 \angle 58.7^\circ \Omega}{1.15}$$

$$Z_{sec \text{ limit}} = 6.9873 \angle 58.7^\circ \Omega$$

$$\theta_{\text{transient load angle}} = 58.7^\circ$$

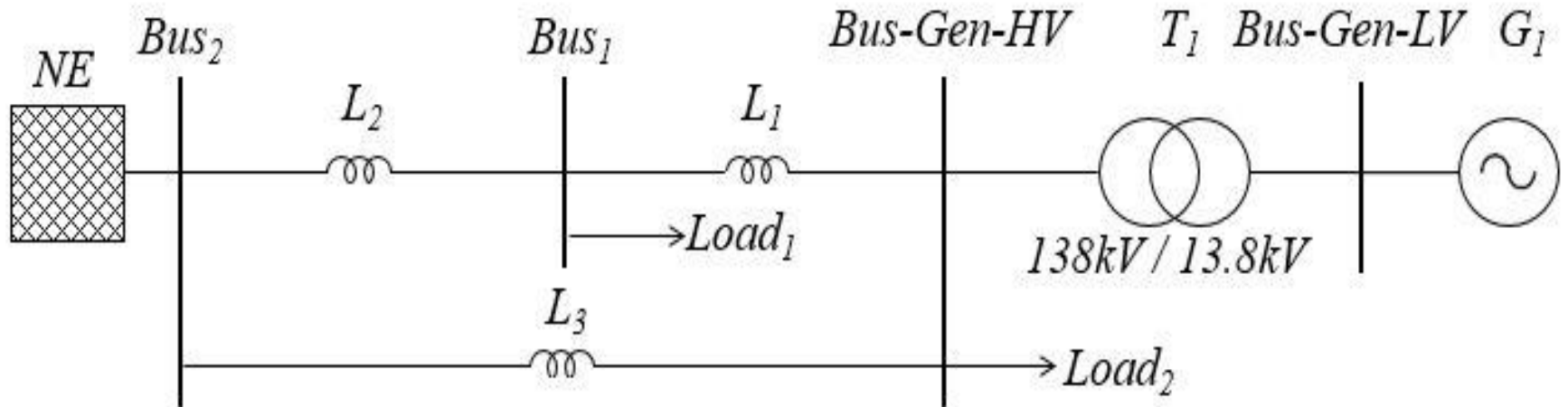
NERC PRC-026-1

PRC-026-1 — Relay Performance During Stable Power Swings

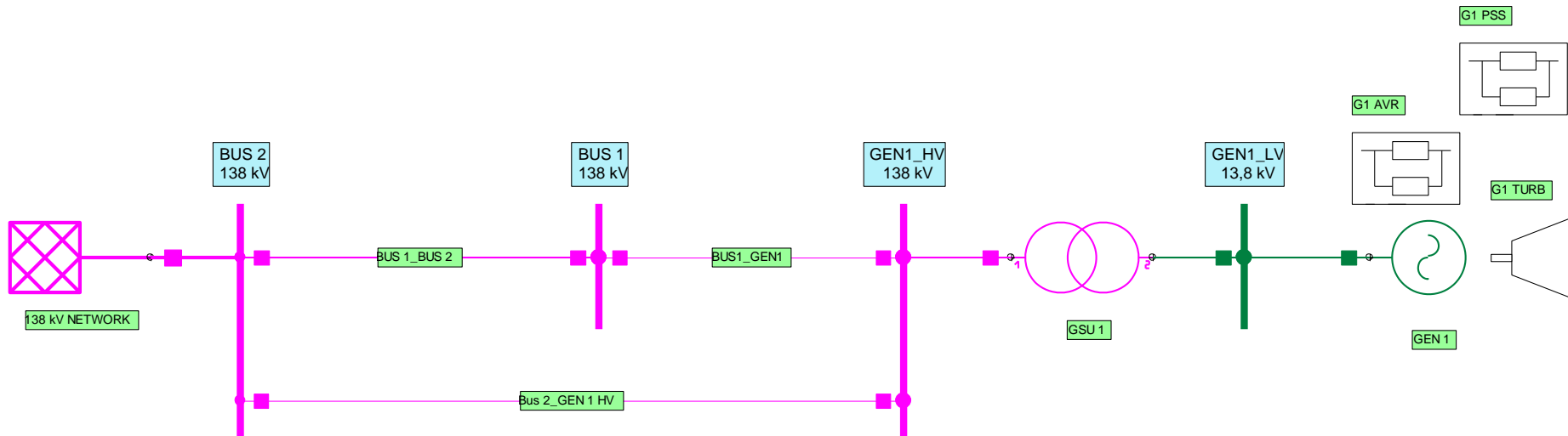
A. Introduction

1. **Title:** Relay Performance During Stable Power Swings
2. **Number:** PRC-026-1
3. **Purpose:** To ensure that load-responsive protective relays are expected to not trip in response to stable power swings during non-Fault conditions.

Case Example - Single line drawing



Case Example Modeling



Case Example Data

System Data

Equivalent System	Data
3 Phase Short Circuit	2.19 kA
Rated Voltage	138 kV
Xs	35.245 Ohm
Rs	9.022 Ohm

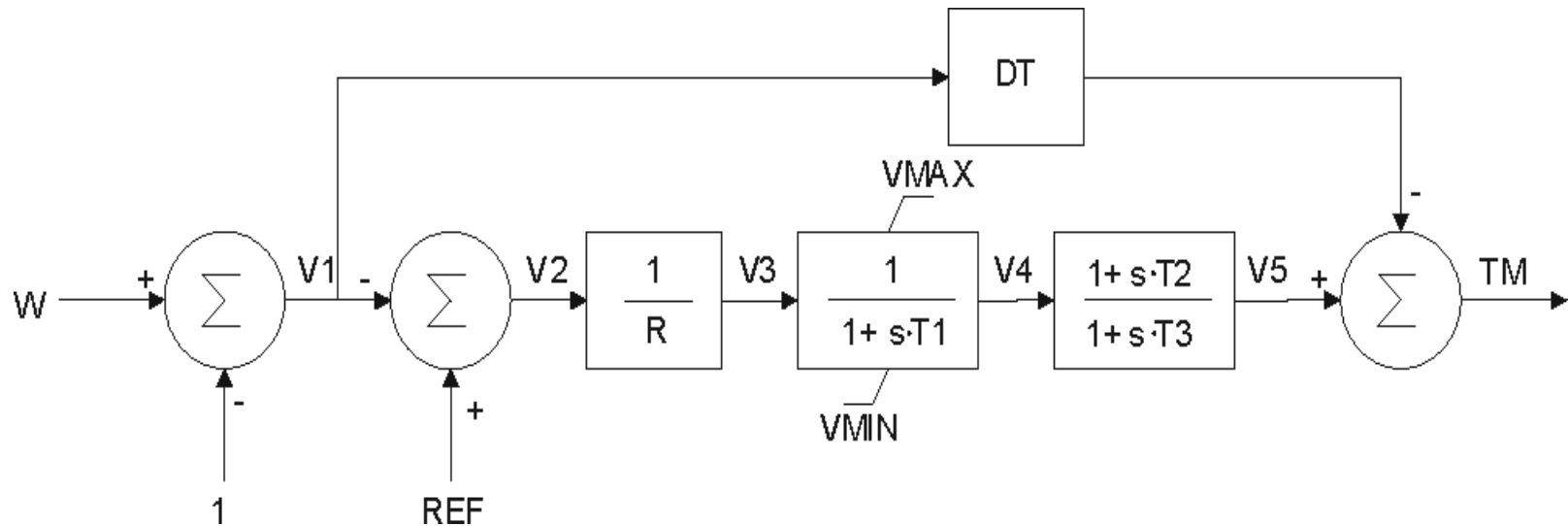
Transformer Data

Transformer	Data
Rated Power	100 MVA
Voltage	138/13.8 kV
Xt	9.27 %

Generator Data

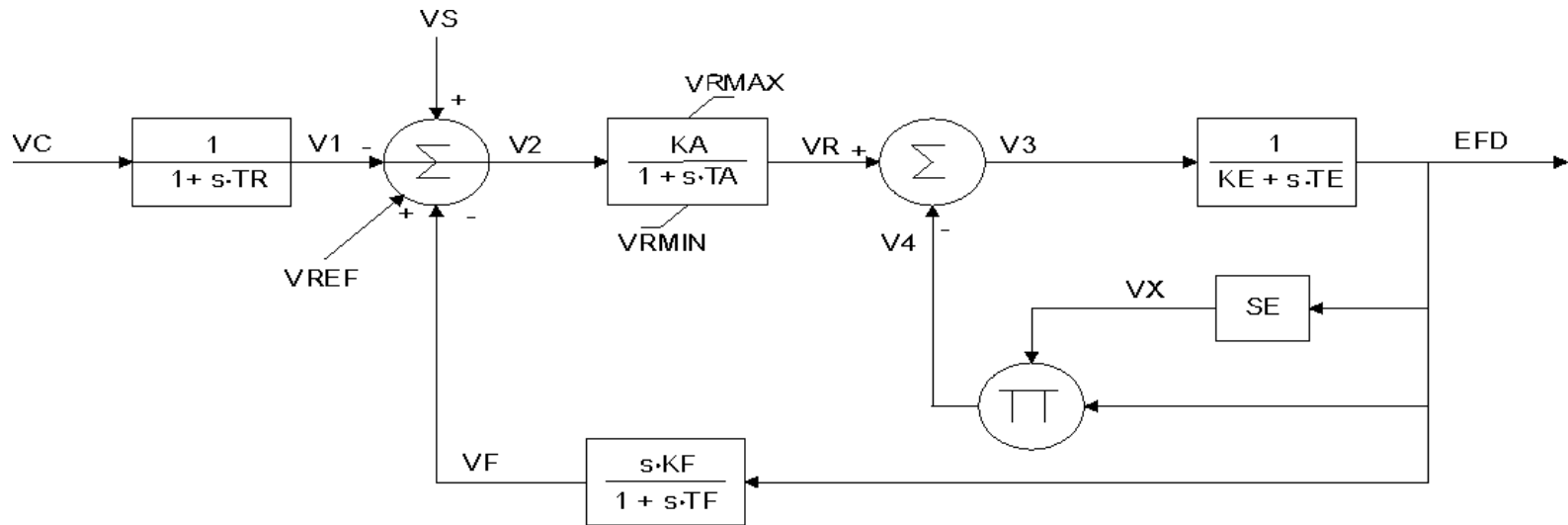
Generator	Data
Rated Power	101.8 MVA
Rated Current	4259
Xd ^{''}	11.7 %
Xd'	16.3 %
Xd	198 %
Turbine	TGOV1
AVR	IEEE T1
PSS	IEEE PSS 1A
Turbine	TGOV1
AVR	IEEE T1
PSS	IEEE PSS 1A

Governor Control



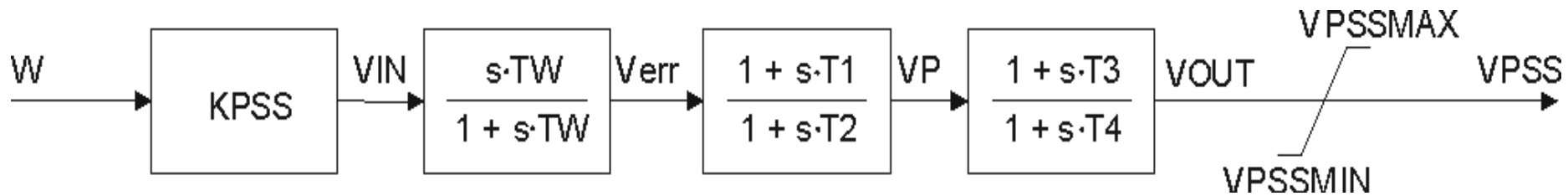
The governor control model is TGOV1

AVR Control



The AVR control System is IEEE11

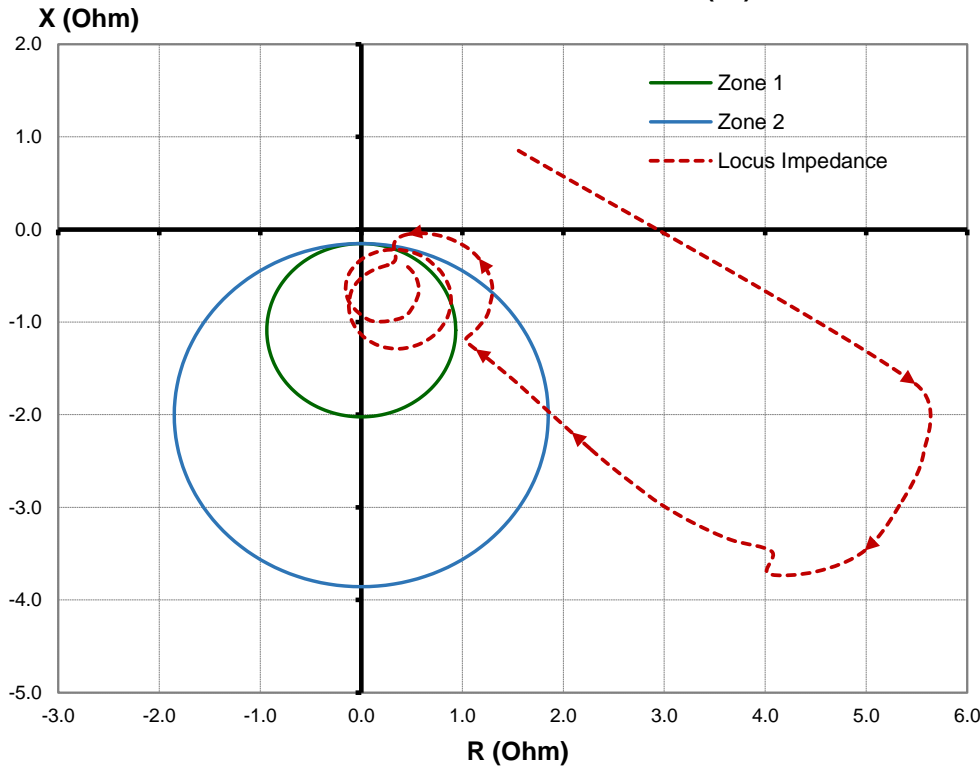
PSS Control



The PSS control System corresponds to IEEE PSS1A

Calculation of Function 40 Settings

EVALUATION LOSS OF FIELD (40)



<u>Characteristic 1</u>	X	Y
Center	0.00	-1.09
Radius	0.94	

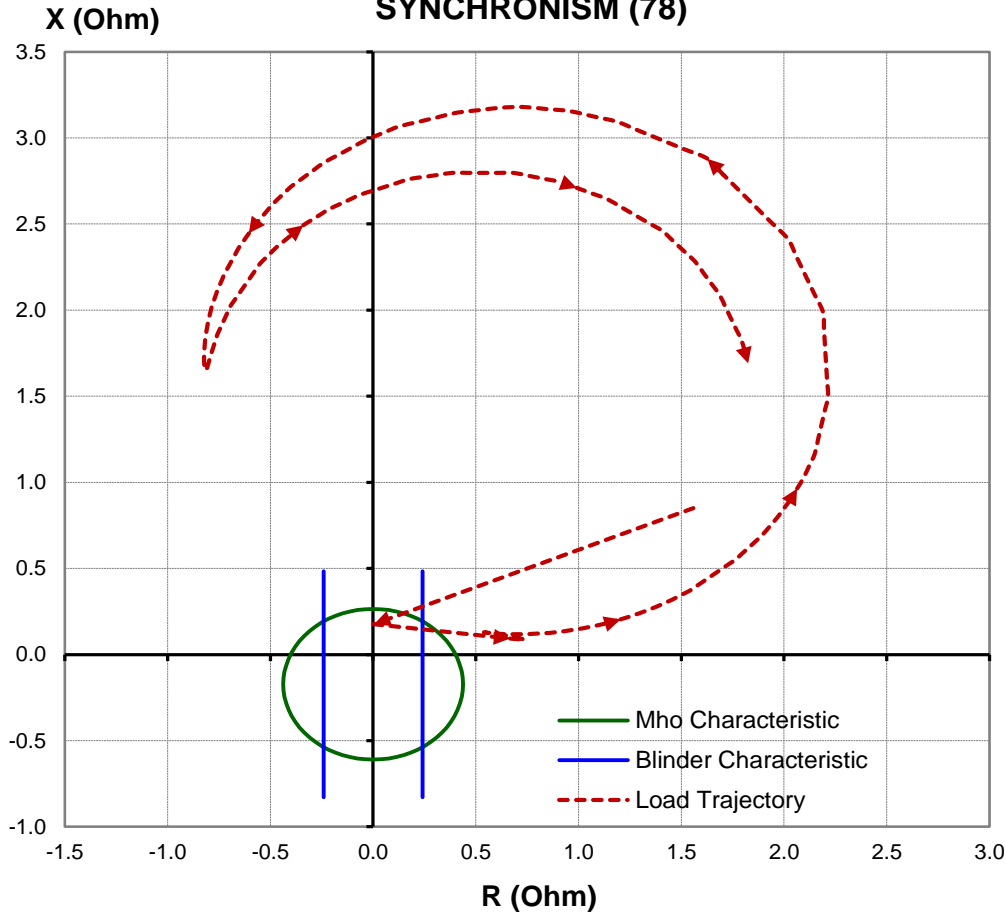
<u>Characteristic 2</u>	X	Y
Center	0.00	-2.00
Radius	1.85	

Angle	<u>Zone 1</u>		<u>Zone 2</u>		<u>Locus Impedance</u>		
	X	Y	X	Y	time	X(R)	Y(X)
0	0.935	-1.088	1.852	-2.004	0.000	1.559	0.850
5	0.932	-1.006	1.845	-1.843	0.005	1.559	0.850
10	0.921	-0.925	1.824	-1.683	0.010	1.559	0.850
15	0.903	-0.846	1.789	-1.525	0.015	1.559	0.850
20	0.879	-0.768	1.740	-1.371	0.020	1.559	0.850
25	0.848	-0.693	1.678	-1.222	0.025	1.559	0.850
30	0.810	-0.620	1.604	-1.078	0.030	1.559	0.850
35	0.766	-0.551	1.517	-0.942	0.035	1.559	0.850
40	0.717	-0.487	1.419	-0.814	0.040	1.559	0.850
45	0.661	-0.426	1.310	-0.695	0.045	1.559	0.850
50	0.601	-0.371	1.190	-0.586	0.050	1.559	0.850
55	0.537	-0.322	1.062	-0.487	0.055	1.559	0.850
60	0.468	-0.278	0.926	-0.401	0.060	1.559	0.850
65	0.395	-0.240	0.783	-0.326	0.065	1.559	0.850
70	0.320	-0.209	0.633	-0.264	0.070	1.559	0.850
75	0.242	-0.184	0.479	-0.216	0.075	1.559	0.850
80	0.162	-0.167	0.322	-0.181	0.080	1.559	0.850

Calculation of Function 78 Settings

Case 1: Before losing synchronism

OUT OF STEP FUNCTION BEFORE LOSING SYNCHRONISM (78)



Mho Characteristic

	X	Y
Center	0.000	-0.173
Radius	0.437	
Forward	0.265	
Reverse	0.610	

Blinder Characteristic

	d	l
	0.241	0.656
Angle	90	
Offset	0.000	

Mho Characteristic

Angle	X	Y
0	0.437	-0.173
5	0.436	-0.134
10	0.431	-0.097
15	0.422	-0.059
20	0.411	-0.023
25	0.396	0.012
30	0.379	0.046
35	0.358	0.078
40	0.335	0.109
45	0.309	0.137
50	0.281	0.162
55	0.251	0.186
60	0.219	0.206
65	0.185	0.224
70	0.150	0.238
75	0.113	0.250
80	0.076	0.258
85	0.038	0.263
90	0.000	0.265
95	-0.038	0.263

Blinder Characteristic

X	Y
0.241	0.483
0.241	-0.829
-0.241	0.483
-0.241	-0.829

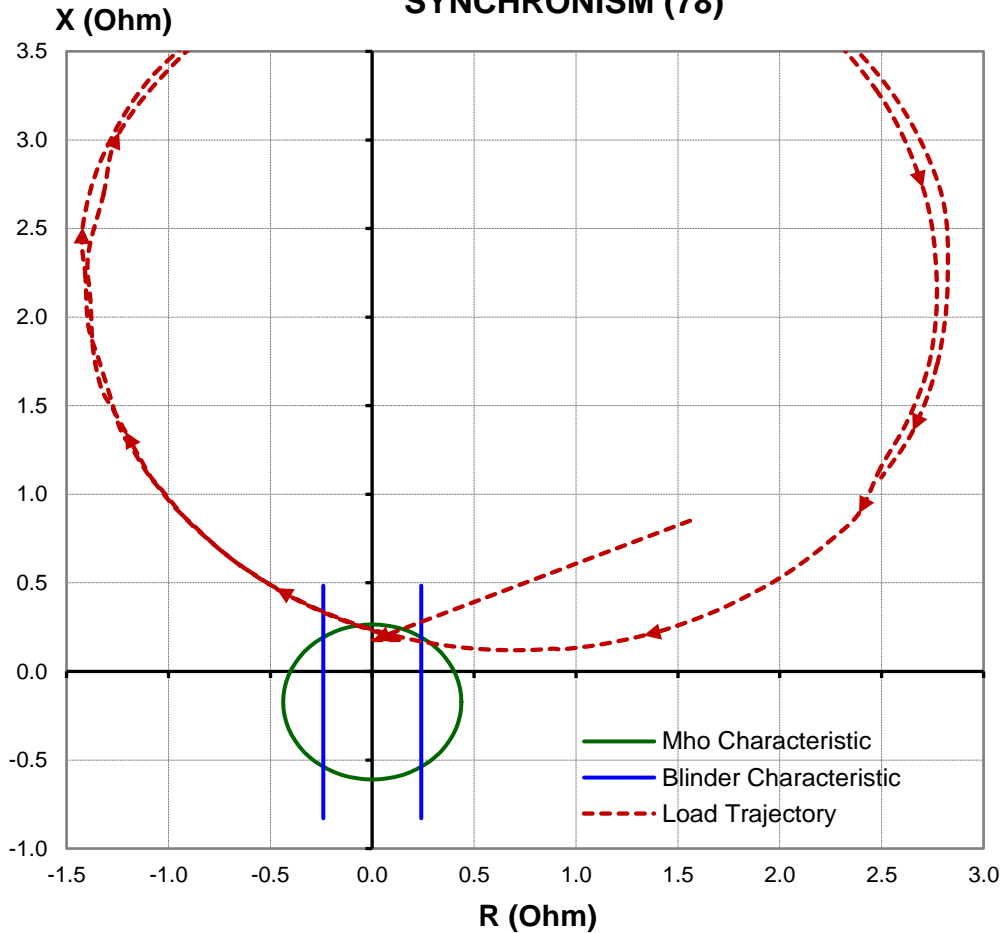
Load Trajectory

t	X(R)	Y(X)
0.000	1.559	0.850
0.001	1.559	0.850
0.002	1.559	0.850
0.003	1.559	0.850
0.004	1.559	0.850
0.005	1.559	0.850
0.006	1.559	0.850
0.007	1.559	0.850
0.008	1.559	0.850
0.009	1.559	0.850
0.010	1.559	0.850
0.011	1.559	0.850
0.012	1.559	0.850
0.013	1.559	0.850
0.014	1.559	0.850
0.015	1.559	0.850
0.016	1.559	0.850
0.017	1.559	0.850
0.018	1.559	0.850
0.019	1.559	0.850

Calculation of Function 78 Settings

Case 2: After losing synchronism

OUT OF STEP FUNCTION AFTER LOOSING SYNCHRONISM (78)



Mho Characteristic

	X	Y
Center	0.000	-0.173
Radius	0.437	
Forward	0.265	
Reverse	0.610	

Blinder Characteristic

	d	l
	0.241	0.656
Angle	90	
Offset	0.000	

Mho Characteristic

Angle	X	Y
0	0.437	-0.173
5	0.436	-0.134
10	0.431	-0.097
15	0.422	-0.059
20	0.411	-0.023
25	0.396	0.012
30	0.379	0.046
35	0.358	0.078
40	0.335	0.109
45	0.309	0.137
50	0.281	0.162
55	0.251	0.186
60	0.219	0.206
65	0.185	0.224
70	0.150	0.238
75	0.113	0.250
80	0.076	0.258
85	0.038	0.263
90	0.000	0.265
95	-0.038	0.263

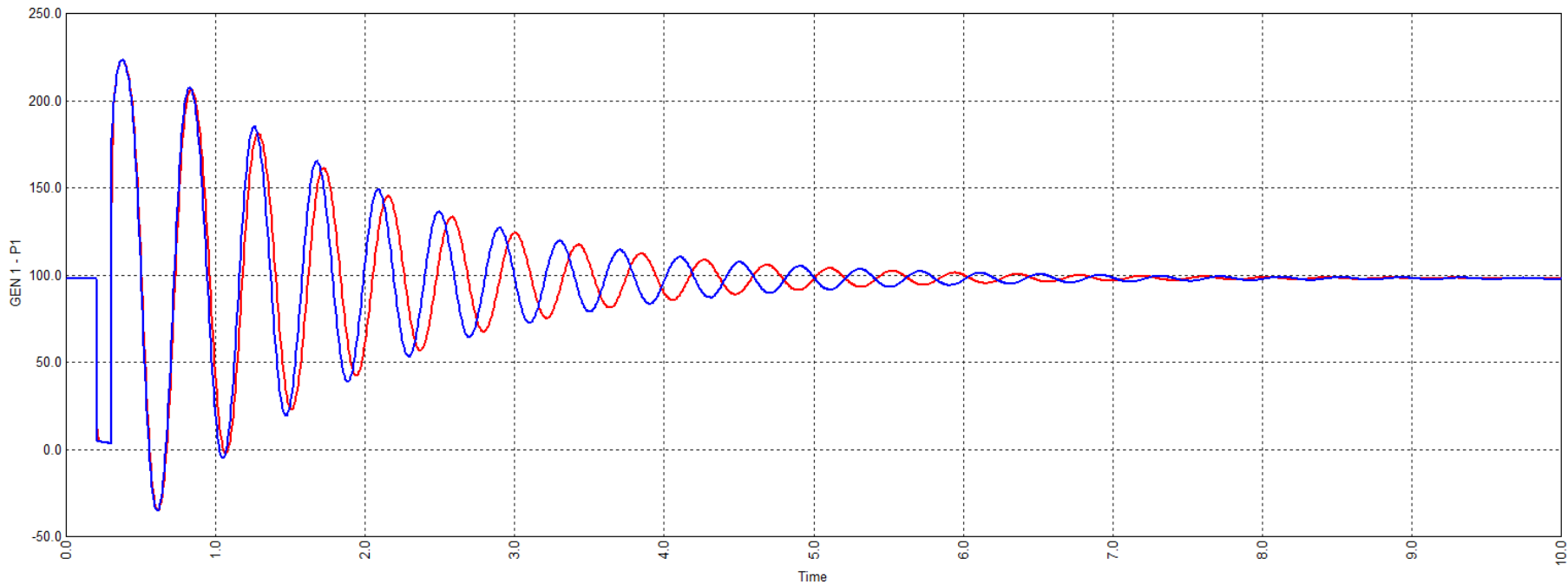
Blinder Characteristic

X	Y
0.241	0.483
0.241	-0.829
-0.241	0.483
-0.241	-0.829

Load Trajectory

t	X(R)	Y(X)
0.000	1.559	0.850
0.001	1.559	0.850
0.002	1.559	0.850
0.003	1.559	0.850
0.004	1.559	0.850
0.005	1.559	0.850
0.006	1.559	0.850
0.007	1.559	0.850
0.008	1.559	0.850
0.009	1.559	0.850
0.010	1.559	0.850
0.011	1.559	0.850
0.012	1.559	0.850
0.013	1.559	0.850
0.014	1.559	0.850
0.015	1.559	0.850
0.016	1.559	0.850
0.017	1.559	0.850
0.018	1.559	0.850
0.019	1.559	0.850

Power comparison before losing synchronism



Without Controls: GEN 1 - P1
Rootnet: GEN 1 - P1

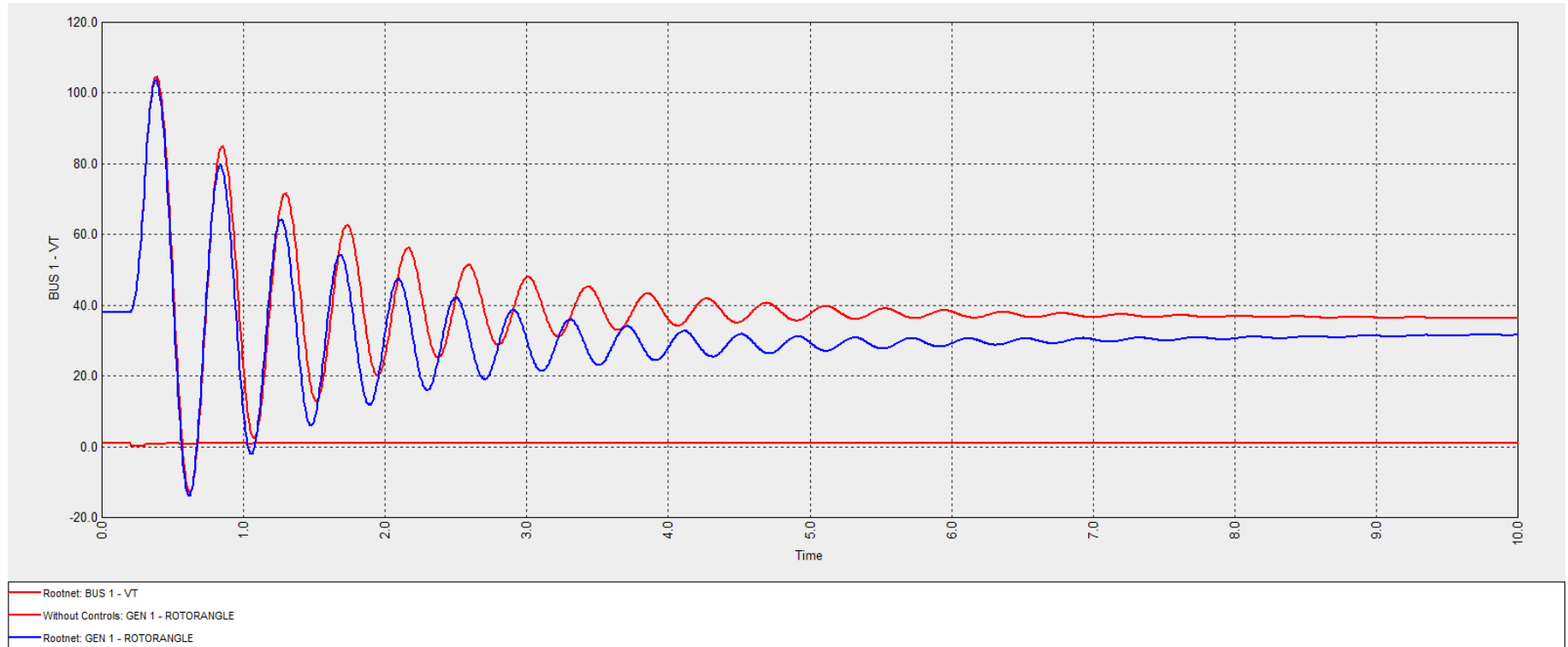
User:
Date:6-6-2018
Plot:Active Power Comparison
NEPLAN

GERS S.A
<http://gers.com.co/>

The active power recovers faster thanks to the controls

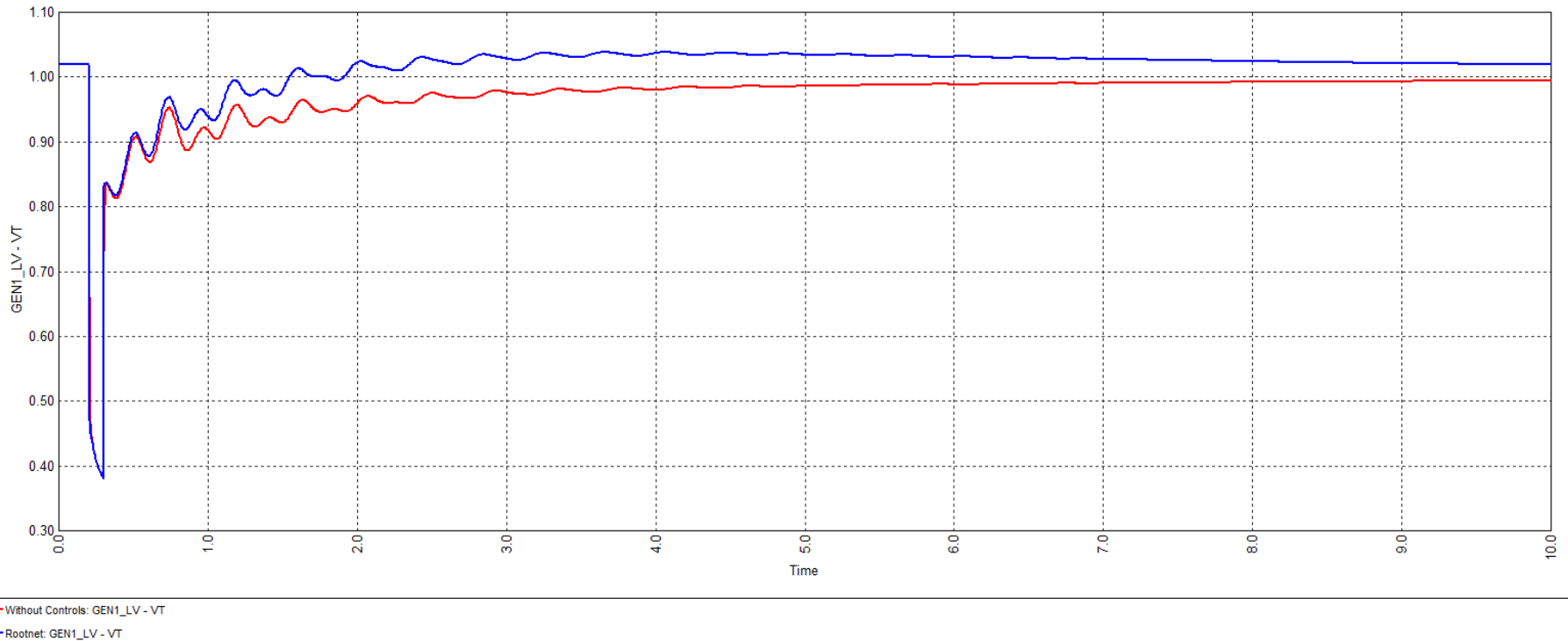


Angle comparison before losing synchronism



The angle adjusts to a different value thanks to the controls

Voltage comparison before losing synchronism



The voltage recovers the initial value thanks to the controls

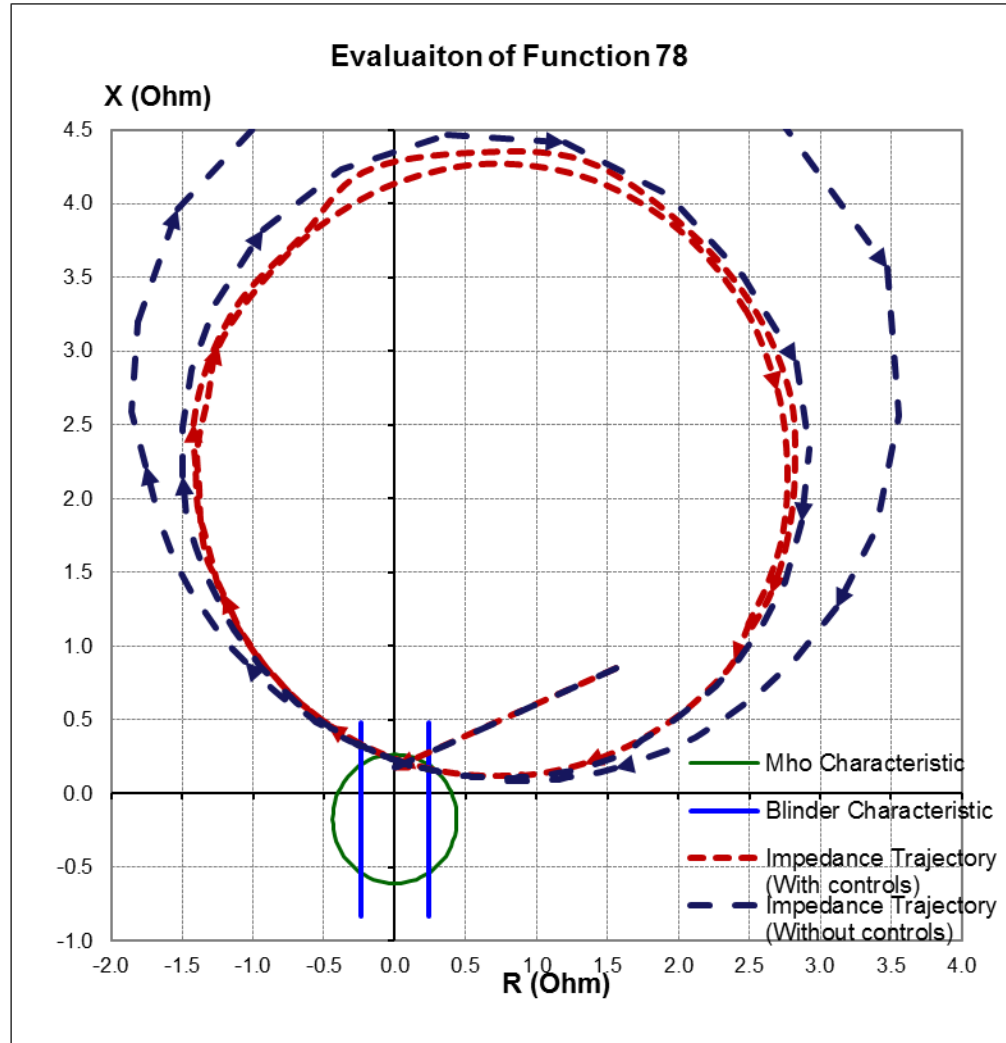
Calculation of Function 78 Settings

After losing synchronism with and without controls

Mho Characteristic												
	X	Y										
Center	0.000	-0.173										
Radio	0.437											
Forward	0.265											
Reverse	0.610											
Blinder Characteristic												
	d	l										
	0.241	0.656										
Angle	90											
Offset	0.000											
Mho Characteristic			Blinder Characteristic		Impedance Trajectory (With controls)			Impedance Trajectory (Without controls)				
Angle	X	Y	X	Y	t	X(R)	Y(X)	t	X(R)	Y(X)		
0	0.437	-0.173	0.241	0.483	0.000	1.559	0.850	0.000	1.559	0.850		
5	0.436	-0.134	0.241	-0.829	0.001	1.559	0.850	0.001	1.559	0.850		
10	0.431	-0.097			0.002	1.559	0.850	0.002	1.559	0.850		
15	0.422	-0.059	-0.241	0.483	0.003	1.559	0.850	0.003	1.559	0.850		
20	0.411	-0.023	-0.241	-0.829	0.004	1.559	0.850	0.004	1.559	0.850		
25	0.396	0.012			0.005	1.559	0.850	0.005	1.559	0.850		
30	0.379	0.046			0.006	1.559	0.850	0.006	1.559	0.850		
35	0.358	0.078			0.007	1.559	0.850	0.007	1.559	0.850		
40	0.335	0.109			0.008	1.559	0.850	0.008	1.559	0.850		
45	0.309	0.137			0.009	1.559	0.850	0.009	1.559	0.850		
50	0.281	0.162			0.010	1.559	0.850	0.010	1.559	0.850		
55	0.251	0.186			0.011	1.559	0.850	0.011	1.559	0.850		
60	0.219	0.206			0.012	1.559	0.850	0.012	1.559	0.850		
65	0.185	0.224			0.013	1.559	0.850	0.013	1.559	0.850		
70	0.150	0.238			0.014	1.559	0.850	0.014	1.559	0.850		
75	0.113	0.250			0.015	1.559	0.850	0.015	1.559	0.850		
80	0.076	0.258			0.016	1.559	0.850	0.016	1.559	0.850		
85	0.038	0.263			0.017	1.559	0.850	0.017	1.559	0.850		
90	0.000	0.265			0.018	1.559	0.850	0.018	1.559	0.850		
95	-0.038	0.263			0.019	1.559	0.850	0.019	1.559	0.850		
100	-0.076	0.258			0.020	1.559	0.850	0.020	1.559	0.850		
105	-0.113	0.250			0.021	1.559	0.850	0.021	1.559	0.850		

Calculation of Function 78 Settings

After losing synchronism with and without controls



Conclusions

- The interaction of governor, AVR and PSS controls in the generators and protective relays strongly determine the stability of a power system.
- Modeling of dynamic of the power system and protection devices permit studying with depth those conditions that may affect the integrity of the power system.
- For stability simulation, the representation of generator protection is necessary.
- Computational collaboration of transient stability programs with specialized protective relay model software is possible.
- Relay models may be used to justify compliance with NERC standards (PRC-019, PRC-024, PRC-025, PRC-026, and others).
- Relay settings included in the models could be used to present graphical results of coordination of generator controls with loss of field, voltage, frequency and other generator protection functions.

Questions?