



Sistemas HVDC

SESIÓN 3 :
Estado del arte en Metodologías y modelos para HVDC

HVDC Modelling for Project Planning Studies

Modelado HVDC para estudios de planificación de proyectos



CHANDANA KARAWITA
TransGrid Solutions Inc. - Canadá





HVDC Planning Studies



- Feasibility Studies
- Steady State Power flow Studies
 - AC system upgrades
 - Voltage stability
 - Reactive power management
 - Special Protection Scheme requirements
- Transient stability assessment
 - Impact on AC system transient stability
 - Control requirements
 - Dynamic reactive power requirements
 - Frequency/inertia support
 - Special Protection Scheme requirements





HVDC Planning Studies



- Technology studies
 - In order to identify capabilities and limitations of new technologies
 - What to ask/expect from a manufacturer
- AC system harmonic evaluation
 - Harmonic impedance profile
 - Background harmonic measurements
- Cost evaluation
- Site selection
- Environmental impact assessment



Challenges in HVDC Planning

- Multiple HVDC options (monopole, bipole, etc.)
- Multiple technologies (LCC or VSC)
- Multiple converter technologies for VSC (half bridge, full bridge, hybrid)
- No manufacturer is selected
- Performance and system impact need to be evaluated through studies



HVDC Simulation models



Motivation for Accurate Models



Accuracy of system study results rely on the accuracy of the models/data used to perform the study!

- This is very important when performing system studies:
 - Transmission systems are planned, designed and built on the basis of such studies
 - If study results are inaccurate due to “bad” models, implications could include:
 - Cost – system is over-designed e.g. too many synchronous condensers installed, unnecessary reactive power capabilities
 - Reliability – system is under-designed e.g. too few synchronous condensers installed – may lead to system instability or load shedding

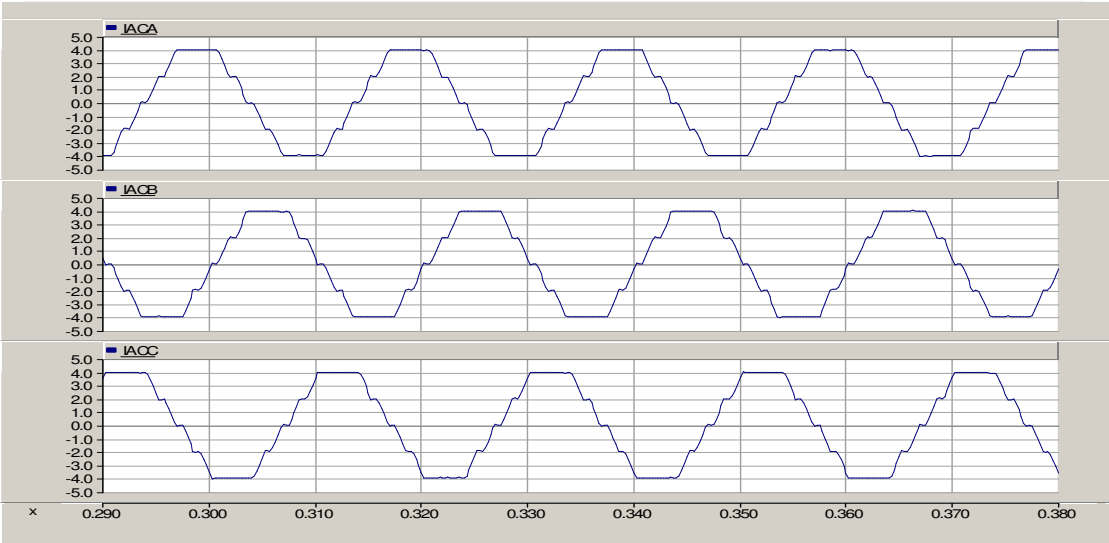




Simulation Models



- EMT Models
 - Detailed converter model including switching logics
 - Detailed controllers
 - Frequency dependent modelling of DC transmission



Simulation Models

- Transient Stability Models
 - Approximated models (fundamental frequency positive sequence)
 - PI section models for DC transmission system
 - Controllers may or may not be modeled in detail

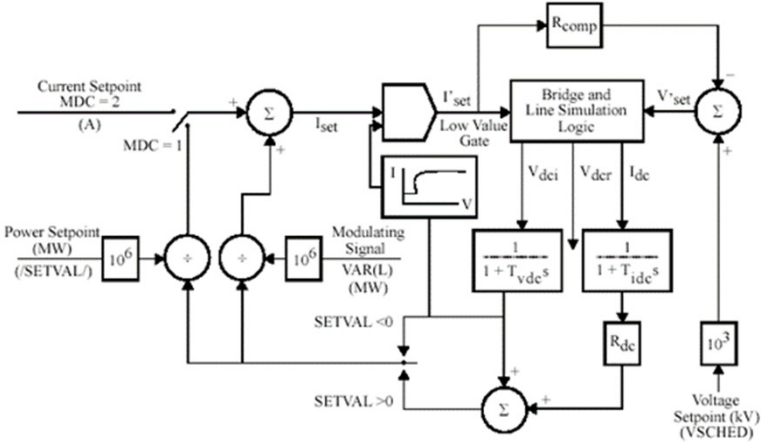


Figure 18-4. CDC4 dc Transmission Control Arrangements

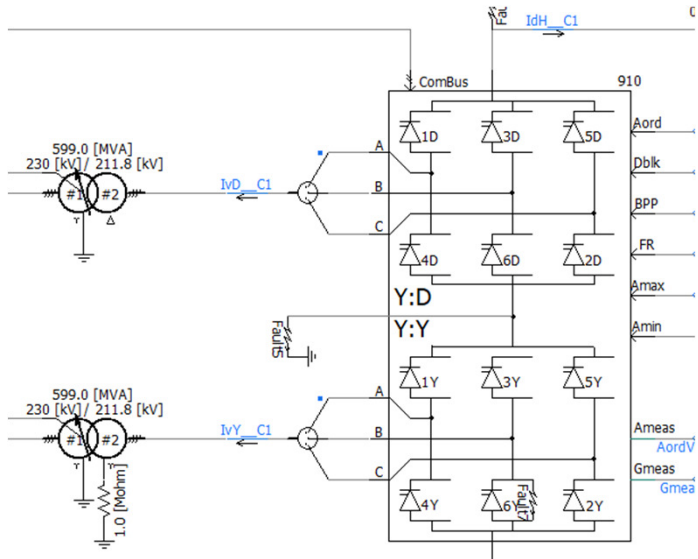
Source: PSSE Manual

Procedure adapted by TGS

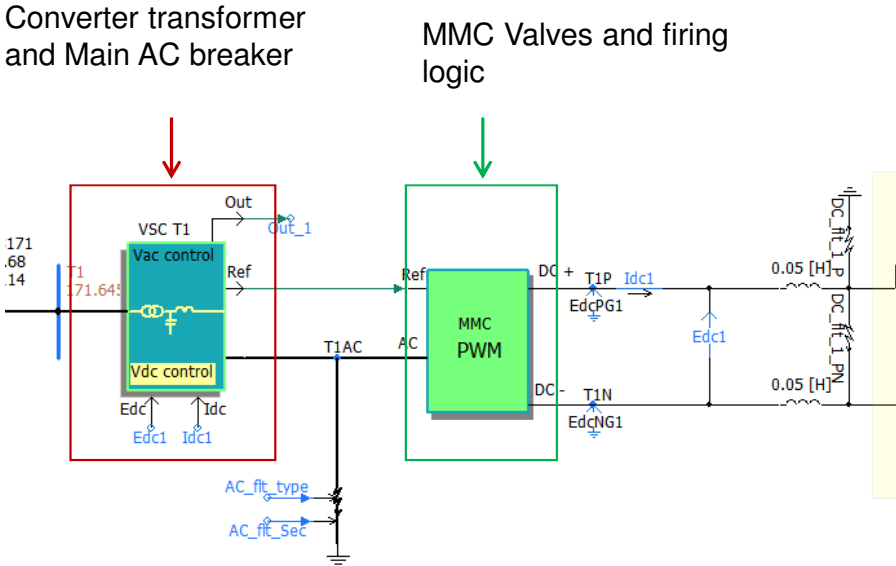
1. Develop a generic EMT simulation model
2. Tune the controllers to get an acceptable performance at the min/max short circuit strengths at the terminals
3. Select a suitable transient stability model
4. Benchmark the transient stability model against the EMT model
5. Perform system studies using benchmarked transient stability model

- Converter Models

12 pulse thyristor bridge for LCC HVDC



MMC converter model for VSC HVDC



EMT Models for Planning Studies

- Controllers

LCC HVDC

- Rectifier current/power controller
- Inverter extinction angle/DC voltage controller
- Inverter current margin controller
- Voltage dependent current order limiters (VDCL)
- DC fault clearing logics (e.g. forced retard)
- Thyristor firing logic

VSC HVDC

- Active power/DC voltage controller
- Reactive power/AC voltage controller
- Dynamic reactive current injection
- Islanded mode controllers
- Inner d-q current controllers
- Converter current/voltage limiting logics
- DC fault clearing logics

EMT Models for Planning Studies

- Controllers

Common Controllers

- Phase locked loop (PLL)
- Frequency controllers
- Power oscillation damping controllers
- Sub-synchronous damping controller
- Run ups and run backs (Special Protection Systems)

Typical Transient Stability Models

- Response-type
- No DC voltage or current controllers – because of small time constants
- Assumes instantaneous jumps in dc voltage and current
- All dc injections based solely on steady state dc equations
- Model is programmed to recover from faults in a pre-set manner





Typical Transient Stability Models



PROS

- Can be run using the large 1/2 cycle time-step used in most transient stability applications

CONS

- Requires user to enter many parameters, such as voltage and current ramp rates
- Different power flow and system conditions may require different sets of parameters
- Can be very time-consuming
- Especially for inverter-side faults and commutation failures, not very accurate
- DC transmission L-R-C dynamics missing





Transient Stability Models -Possible Solutions



- Hybrid simulations
 - HVDC and a small part of the AC network are modeled in an EMT environment and combined with a large network in a transient stability environment
 - Large modelling effort
 - Time taken for simulations (usually 100s of simulations)
 - Interfacing issues
 - Validations???



Transient Stability Models -Possible Solutions

- Two-time step simulations
 - HVDC is run at very small time steps (e.g. 50 us)
 - Rest of the system is run at regular time steps (half or quarter cycles)
 - HVDC model is first validated against an EMT model at maximum and minimum system strengths expected at the terminals (tuning & validations)
 - Any number of HVDC systems can be modeled.
 - No burden on the time taken for the transient stability analysis (fast and low cost solutions)



Transient Stability Models -Possible Solutions



- Two-time step simulations
 - TGS has used this approach for many projects and manufacturer detailed model developments
 - 2T LCC HVDC model (in PSSE & PSLF)
 - 3T LCC HVDC model (in PSSE & PSLF)
 - 2T MMC VSC HVDC model (in PSSE, PSLF and DIgSILENT)
 - Half bridge & Full bridge converters
 - Monopole & Bipole configurations
 - DC faults
 - Cleared using fast DC breakers
 - Cleared using AC breakers + mechanical DC breakers
 - Cleared using controlled fault clearing logics
 - DC grid model (with FB VSC converters & LCC converters)
 - MMC STATCOM model





Example: 2T LCC Model



Comparison of performance of PSSE model against PSCAD

3PH Fault at Rec

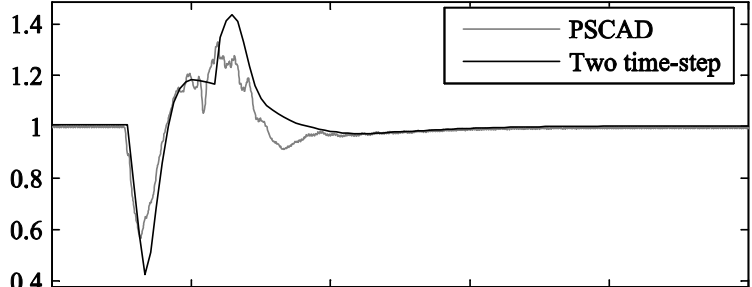
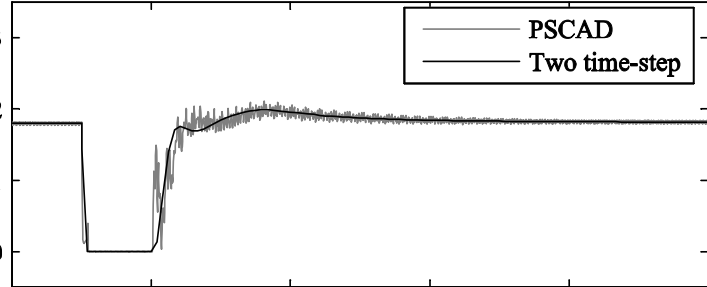
3PH Fault at Inv

Two-time step

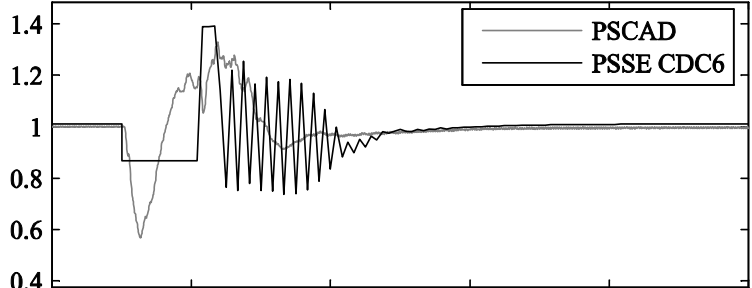
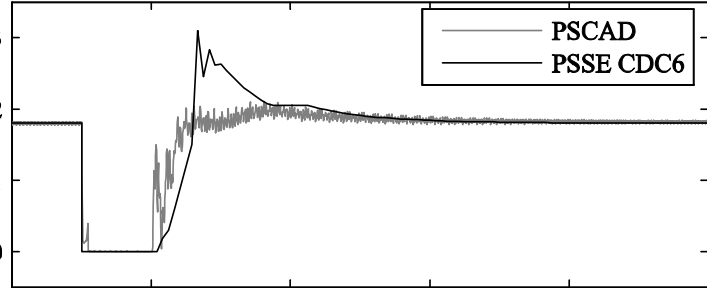


DC current (kA)

Rectifier AC Bus Voltage (pu)



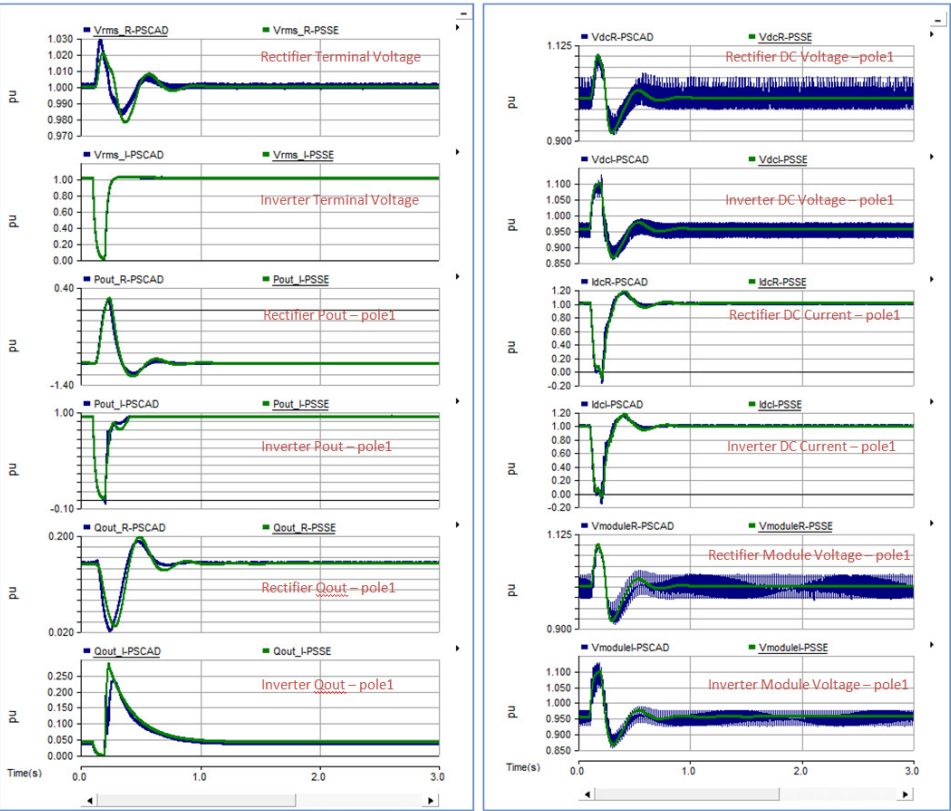
Response type



Example: 2T MMC VSC

- Three phase ac faults at the terminals (fault ride through capability)

Comparison of performance of PSSE model against PSCAD



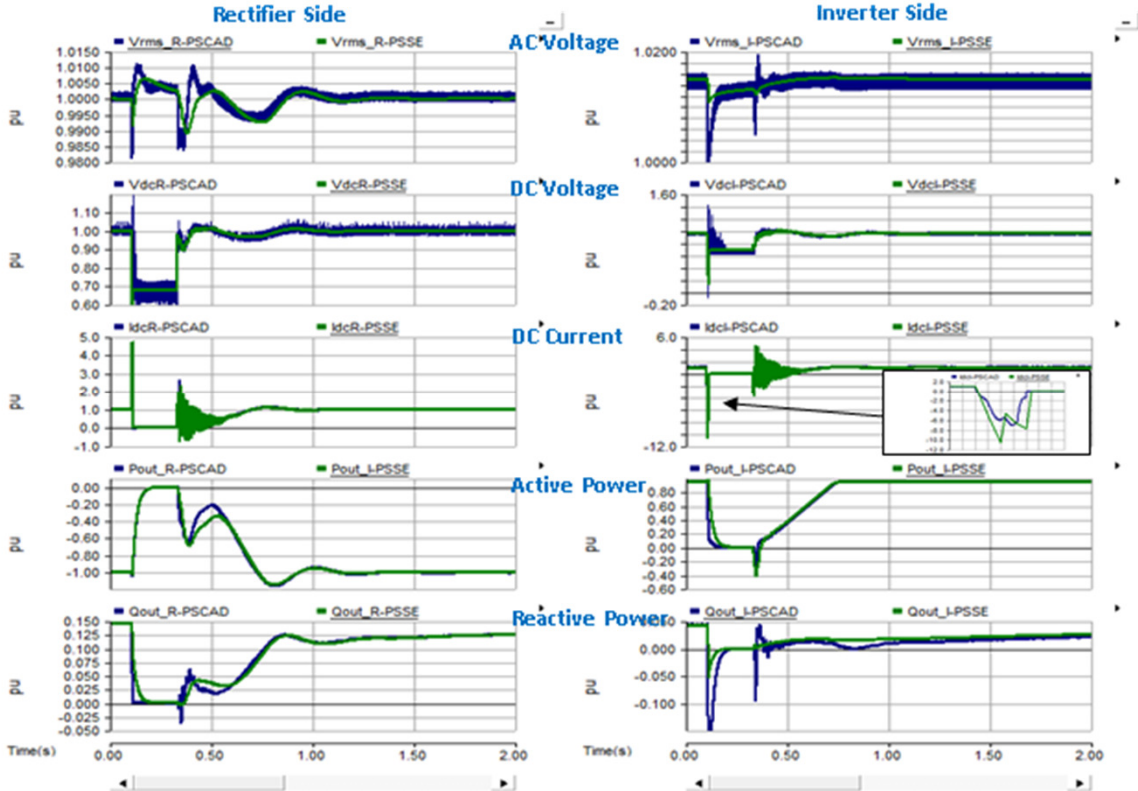


Example: 2T MMC VSC



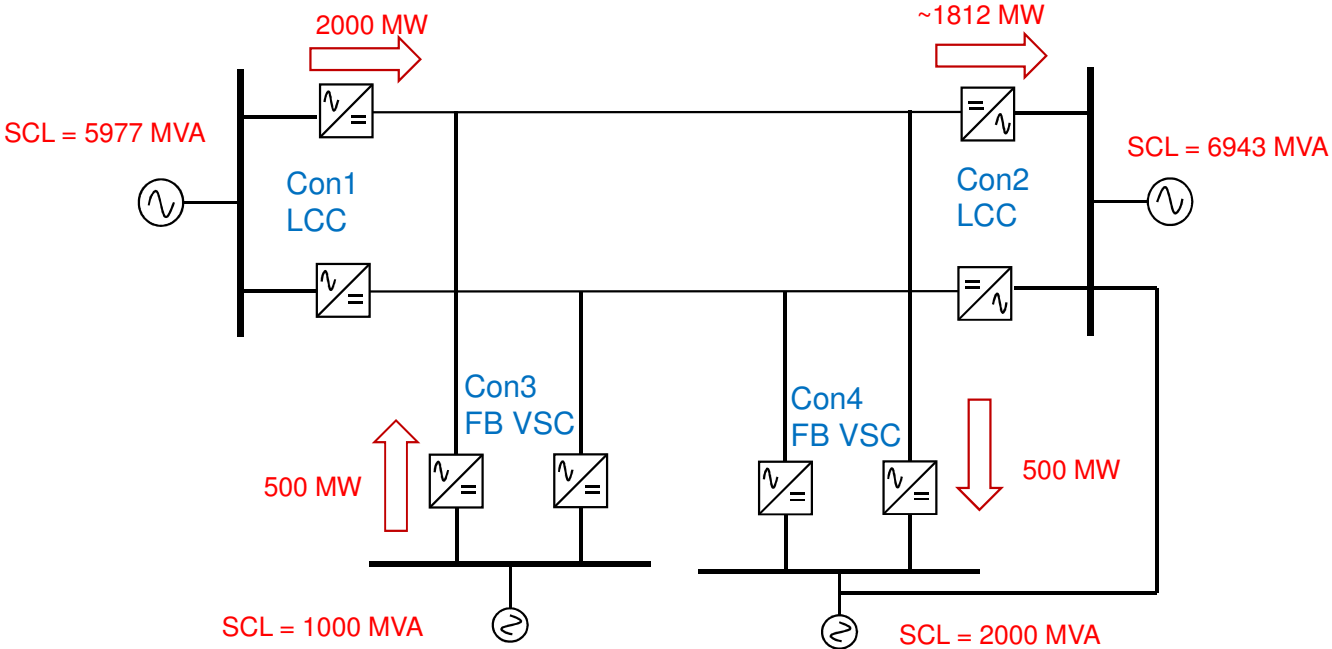
- Inverter Side DC fault Cleared by a Fast DC Breaker

Comparison of performance of PSSE model against PSCAD





DC Grid Example



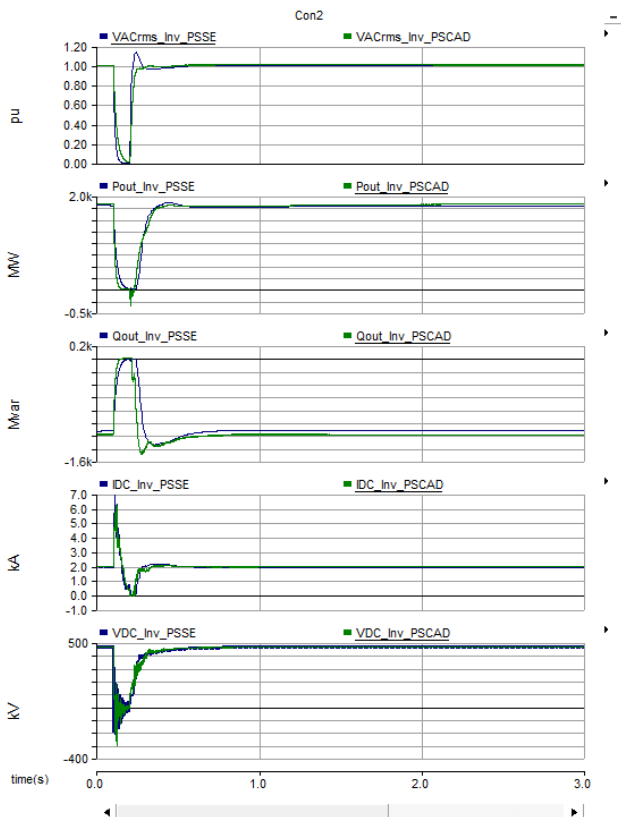
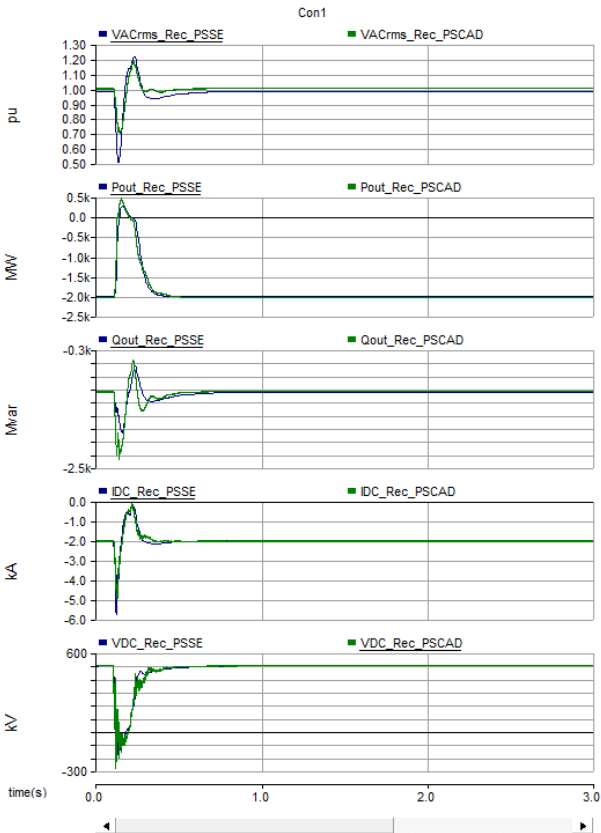
This model was used for Manitoba Hydro Bipole-3 VSC tapping studies





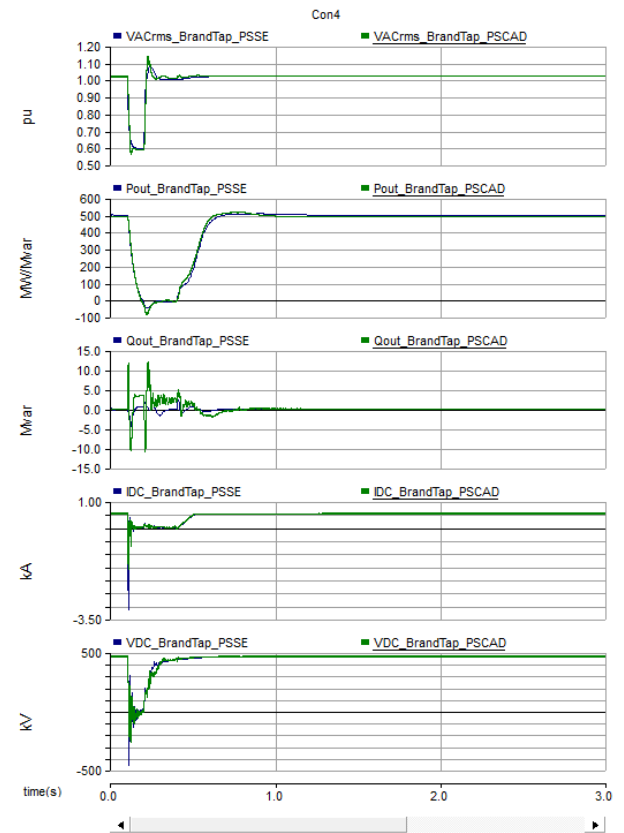
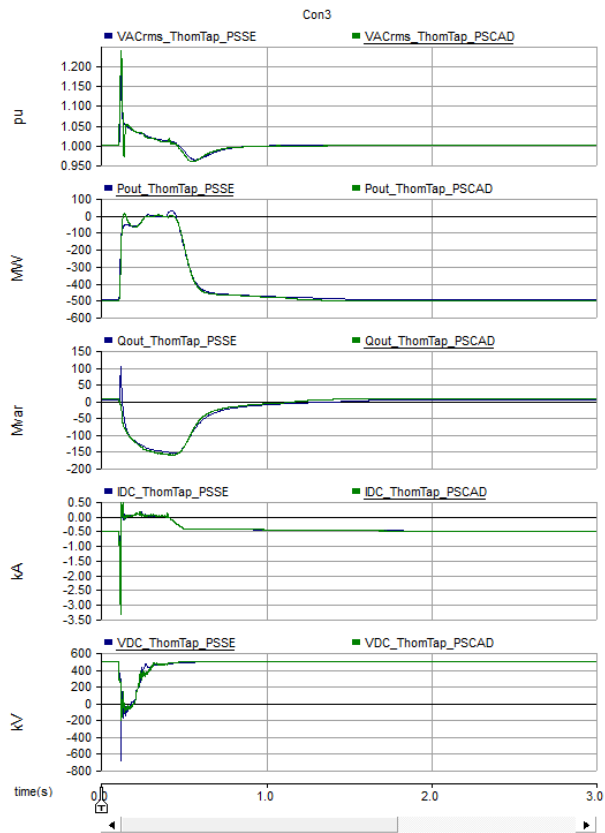
AC Faults

Solid AC fault at Con2 (inverter) – LCC Plots



AC Faults

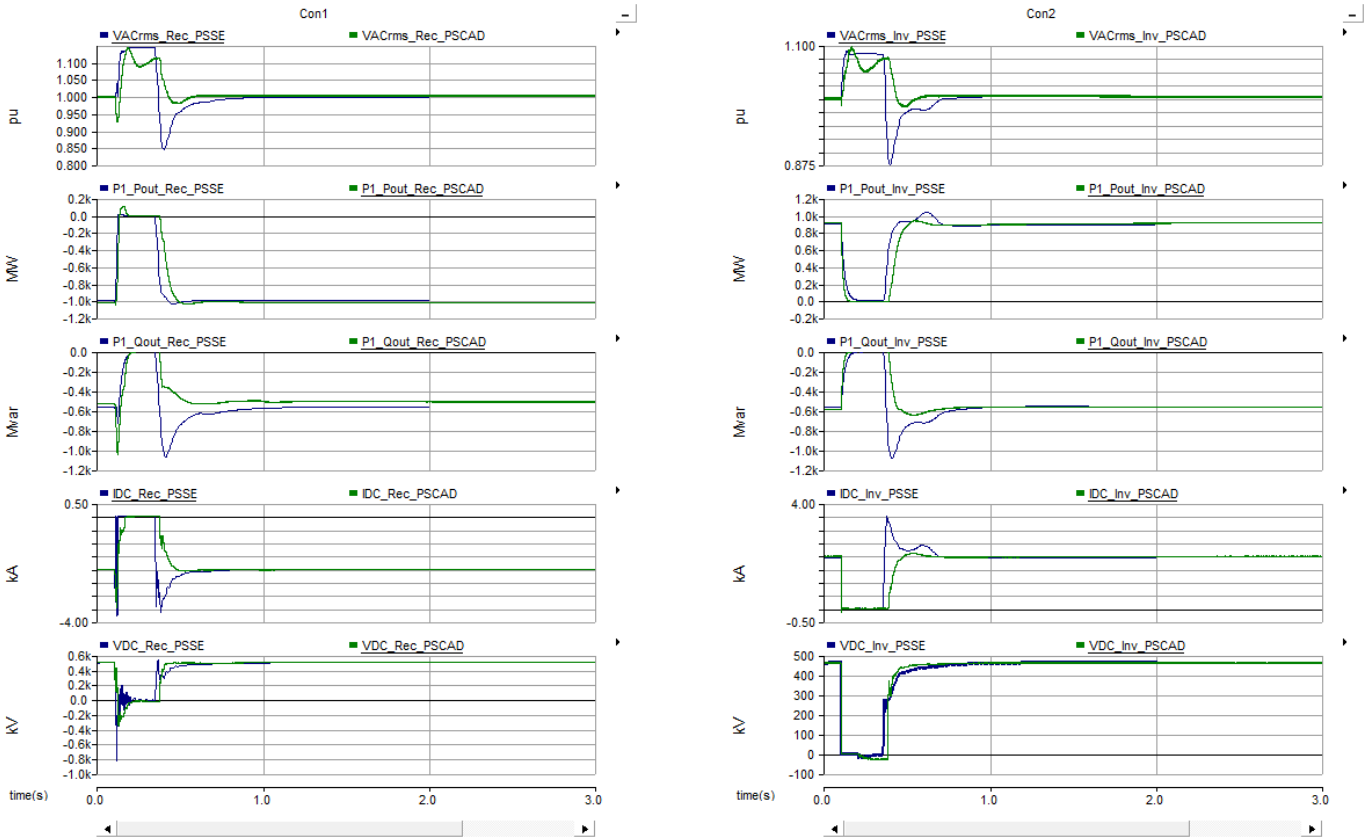
Solid AC fault at Con2 (inverter) – VSC Plots





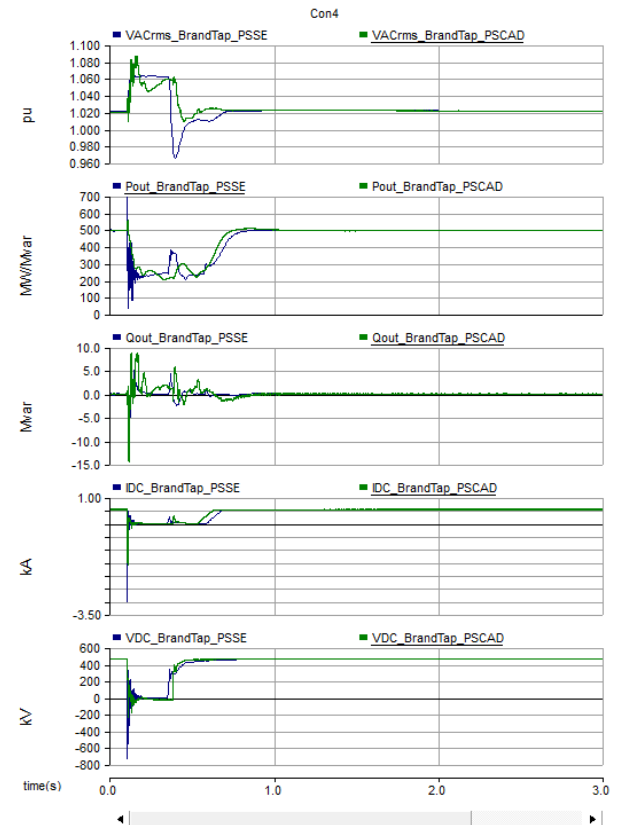
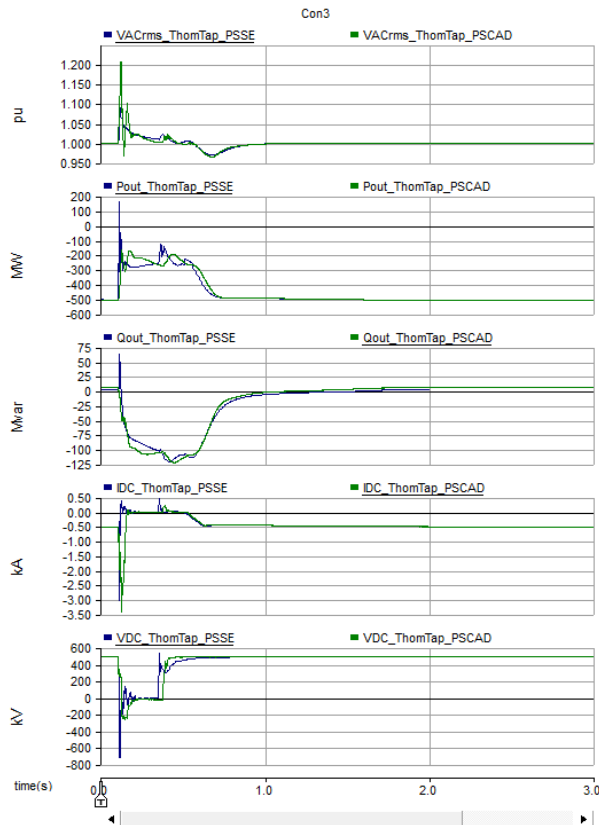
DC Faults

DC fault at Con2 – LCC Plots



DC Faults

DC fault at Con2 – VSC Plots



Summary

- It is very important to model the accurate behavior of HVDC systems for planning studies.
 - Determine system requirements
 - Determine HVDC performance requirements – to be included in the HVDC specification or to evaluate the manufacturer’s designs
- Proper models should be used for proper applications (EMT or TS)
- TGS has adapted “two-time-step” approach for transient stability analysis
 - Accurate results
 - Model set up and simulation is easy
 - Large number of simulations can be done in a short time

Gracias

